

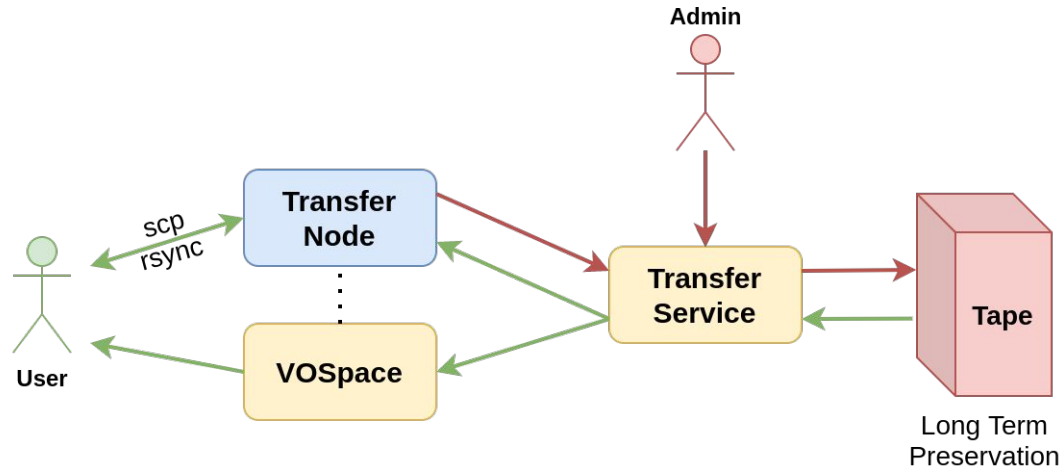
# A VOSpace implementation with tape support

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# IA2 tape use case



New folder Upload files Async recall

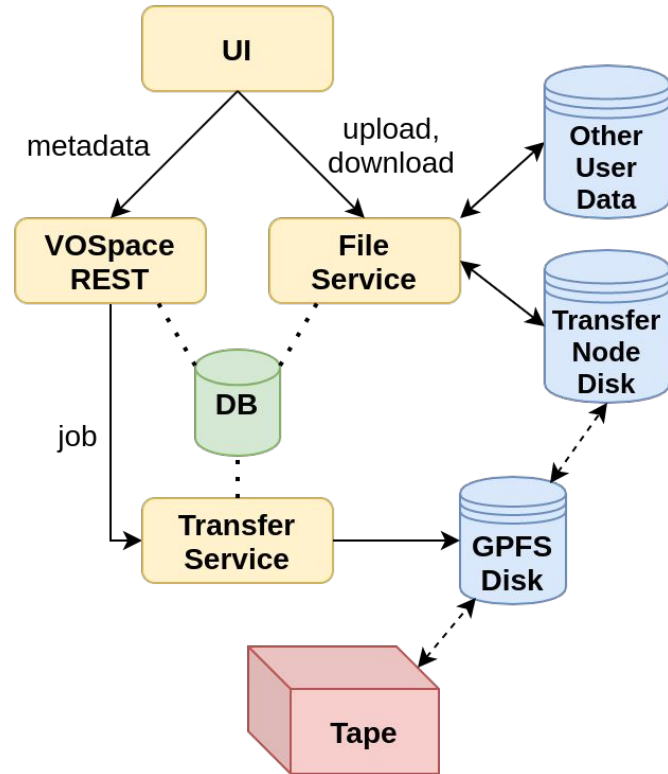
Name

 project1

 project2



# General overview



- pushToVoSpace and pullFromVoSpace endpoints point to File Service
- Transfer Service performs import and export of files from the storage reachable from File Service to the tape and vice versa
- file metadata is stored in a shared database
- A&A based on OAuth2

# Tape async recall

Custom property in node to indicate that data is not immediately available for download:

```
<vos:properties>
  <!-- ... -->
  <vos:property uri="urn:ia2:async-trans">true</vos:property>
</vos:properties>
```

Custom protocol in pullToVoSpace transfer:

```
<vos:transfer xmlns:vos="http://www.ivoa.net/xml/VOSpace/v2.0" version="2.1">
  <vos:target>vos://example.com!vospace/mydir</vos:target>
  <vos:direction>pullToVoSpace</vos:direction>
  <vos:protocol uri="urn:ia2:async-recall"></vos:protocol>
</vos:transfer>
```

# List of files transfer

Use case: user wants to perform an asynchronous recall of multiple nodes (e.g. a subset of files inside a directory).

## Problems:

- VOSpace transfer operations expect **one target node**.
- We can't start multiple jobs (one for each node) because tape library software automatically optimizes the retrieval of a set of files from multiple cartridges.

Current workaround: a temporary StructuredDataNode with a custom view (urn:ia2:list-of-files) is created. It contains the list of nodes to transfer. The pullToVoSpace operation specifies this node as the target.

# Communication with token-based GMS



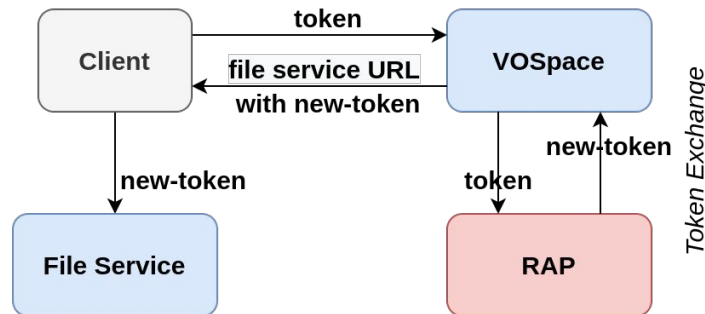
- The same token used for VOSpace is forwarded to GMS (token relay)
- All the groups are retrieved and result is cached for some minutes
- getNode() endpoint returns only the nodes that can be accessed by the user (according to groupRead property), so filtering each node using isMemberOf could be heavyweight

# OAuth2 token exchange in transfers

```
<vos:transfer ...>  
  <vos:target>vos://example.com!vospace/mynode</vos:target>  
  <vos:direction>pushToVoSpace</vos:direction>  
  <vos:protocol uri="ivo://ivoa.net/vospace/core#httpput">  
    <vos:endpoint>http://file-service/mynode?token=eyJ0eXA...</vos:endpoint>  
  </vos:protocol>  
</vos:transfer>
```

RFC 6819: «*If access tokens are sent via URI query parameters, such tokens may leak to log files and the HTTP "referrer".*»

→ a new token with a narrower scope, jti claim and shorter expiration is generated using Token Exchange (RFC 8693)



# “Single-user groups” sharing

**Use case:** user wants to share a node with another user.

We are using special groups in the GMS that are associated with a single user.

```
<vos:property uri="ivo://ivoa.net/vospace/core#groupread">mygroup1 people.user2</vos:property>
```

group of users

special “single-user group”



# Other discussion points

## **Undeleteable nodes**

For some nodes we want that the user can edit their properties (e.g. groupRead) but can't delete them (long term preservation data can't be deleted). We are using a custom property for this (sticky, similar to CADC locked?).

## **Recursive groups update**

We added a parameter to the setNode operation for performing the groupRead and groupWrite update recursively on all child nodes.

## **Folder size**

Total size? Zero? 4 KB (file system block size)?

## **Pagination API**

What if a node contains too many child nodes?

# Used technologies

- File metadata is stored in a PostgreSQL database with ltree extension
- JAXB beans automatically generated from XSD files using XJC
- Spring Boot for the REST service and the File Service
- Jackson combined with JAXB to support both XML and JSON payloads
- Python for the Transfer Service with Redis queues for handling jobs
- Spring Boot + Vue.js for the UI

# Current status

Development is in progress, ready for production in the next months.  
Code available here: <https://www.ict.inaf.it/gitlab/vospace> (still partially private)

Tests with CADC vofs module shown a good level of compatibility.

Thanks for your attention

**Questions?**

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