

A Component and Association Based Model For Source Data

L. Michel F. bonnarel in collaboration with TDIG and CDS and others VO members



Why Doing a Source Model?

For the Science

- Make sure that data, scientifically relevant for a particular use case, are well described.
- To make sure that data sent by a service will be properly understood by the clients.
 - With a system of unambiguous annotations
 - By enabling clients to understand these annotations
 - By making sure that clients could take advantage of these annotations

The model design is not a goal in itself, it is just a (powerfull) tool



Motivation for a Source Model

anary using TA D/SOI

J/A+A/532/A103/IC4665 Photometry and proper motions in IC4665 (Lodieu+, 2011)

plot the output

2011A&A

Post annotation

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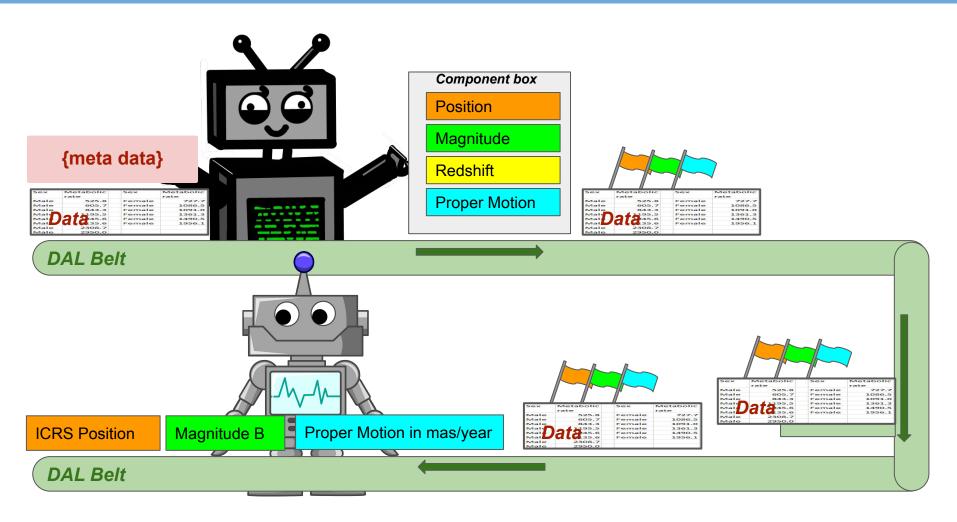
Coordinates, photometry, proper motions, and physical parameters for IC4665 stars (tables A1, B1 and C1 of paper) (1533 rows)

-	start Aladini	Lite //	plot the output	<u>क</u> वा	iery usi	ng TAP	SQL									
F	ull _RAJ2000	_DEJ2000 M	m Name	Zmag	Ymag	Jmag	Hmag	Kmag	pmRA	pmDE	logL	Mass	GCS	Simbad	RAJ2000	DEJ2000
	"h:m:s"	"d:m:s"		mag	mag	mag	mag	mag	mas/yr		[Lsun]	Msun			"h:m:s"	"d:m:s"
4	1 17 42 05 0200		174205 02 052412 0	15 112	14 525	12 940	12 200	12 021	1 00	10.56	1.20	O 440	CCC	Cimbad	17 42 05 02	105 24 12 0
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	<u>3</u> 17 42 09.5800	+05 21 12.600 C	174209.58+052112.6	15.693	15.200	14.587	13.944	13.615	-36.93	-34.57	-1.61	0.267	GCS S	Simbad	17 42 09.58	+05 21 12.6
	4 17 42 16.9500	+05 26 51.300 C	174216.95+052651.3	15.670	15.269	14.676	14.082	13.761	-3.44	3.13	-1.65	0.251	GCS S	Simbad	17 42 16.95	+05 26 51.3
	5 17 42 17.7800	+05 56 26.200 C	174217.78+055626.2	16.616	16.024	15.344	14.767	14.377	-25.95	-12.29	-1.93	0.160	GCS S	Simbad	17 42 17.78	+05 56 26.2
	6 17 42 18.0000	+05 49 25.500 C	174218.00+054925.5	14.923	14.523	13.970	13.353	13.095	-8.36			_				+05 49 25.5
	7 17 42 18.1900	+05 53 53.300 C	174218.19+055353.3	17.047	16,495	15.845	15.246	14.900	17.51			A RESTORATION OF THE PARTY OF T				+05 53 53.3
	8 17 42 20,2900	+05 55 56.500 C	174220.29+055556.5	14.734	14.267	13.654	13.059	12.740	8.68							+05 55 56.5
	The second secon	+05 46 35.600 C	174220.79+054635.6													+05 46 35.6
		+05 43 13.900 C	174221.08+054313.9						6.06							+05 43 13.9
		+05 38 23,500 C	174223.55+053823.5		Part of the State				1.01							+05 38 23.5
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						100000000000000000000000000000000000000			The second second							
		+06 22 19.800 C	174226.60+062219.8		and the second second											+06 22 19.8
	16 17 42 26.9300	+06 20 14.600 C	174226.93+062014.6						-4.73			and the second second				+06 20 14.6
	17 17 42 28.0300	+05 26 40.700 C	174228.03+052640.7	14.683	14.311	13.740	13.129	12.833	4.01	21.98	-1.25	0.481	GCS :	Simbad	17 42 28.03	+05 26 40.7
	18 17 42 28.9300	+05 54 53.800 C	174228.93+055453.8	17.691	17.048	16.427	15.888	15.495	28.31	79.04	-2.39	0.078	GCS S	Simbad	17 42 28.93	+05 54 53.8
	19 17 42 28.9400	+06 20 28.000 C	174228.94+062028.0	15.234	14.810	14.260	13.592	13.286	2.95	7.72	-1.47	0.336	GCS S	Simbad	17 42 28.94	+06 20 28.0
	20 17 42 31.9100	+06 18 49,500 C	174231.91+061849.5	14.560	14.139	13,606	12.988	12,679	-41.07	0.18	-1.19	0.524	GCS S	Simbad	17 42 31.91	+06 18 49.5

How could a client process or even plot Position/Mags/PM/Mass entries of this catalog without taking into consideration it comes from Vizier?



2 Stakeholders: Data Provider/Consumer:



The model is so discreet in this diagram that one may wonder if it exists



Client Perspective

```
MacBook-Pro-de-Laurent-MICHEL:SourceDM laurentmichel$

parser = Parser("My VoTable")

sources = parser.getInstanceSet("CABMSD");

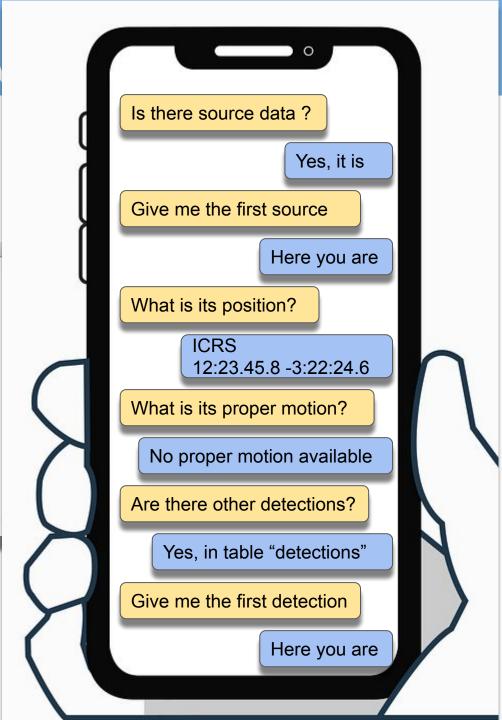
while( sources.hasNext())

source = sources.next()

print(source.get("position"))

print(source.get("mag.G"))
```

MacBook-Pro-de-Laurent-MICHEL:SourceDM laurentmichel\$





CAB-MSD Guideline

We have to consider:

1. The annotation content

- a. Data modeling
 - i. Including the import of VO standards (Meas/Coord NDCube, semantic...,)
- b. Serialization

2. The data annotation process

- a. Data provider point of view
- b. No hope to use the model as long as no data provider implements it

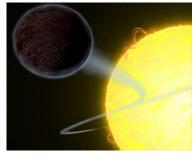
3. The annotated data processing

a. Client developer point of view

All of these are parts of the CAB-MSD project



The Model: Object Types and Params



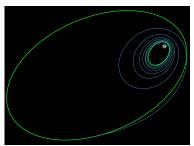
Exoplanets



Orbiting stars



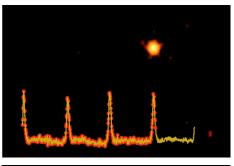
Complex shaped objects



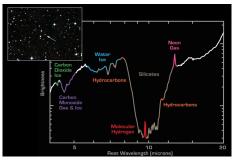
Complex errors



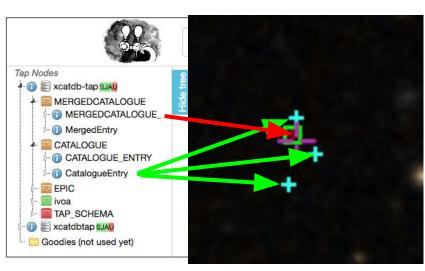
The Model: Associated Data



Time Series



Spectrum



Multiple detections Correlations

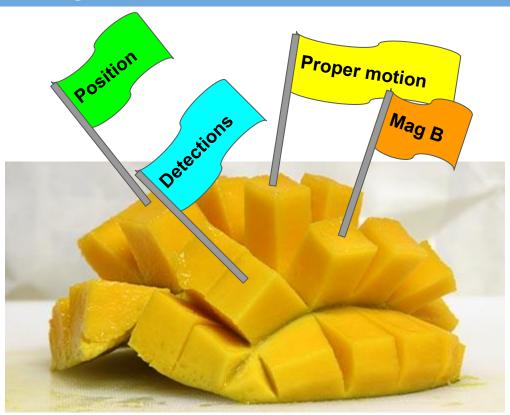


The Model: The Fruity Version



Source Data Model

Everything is well packed in a model instance

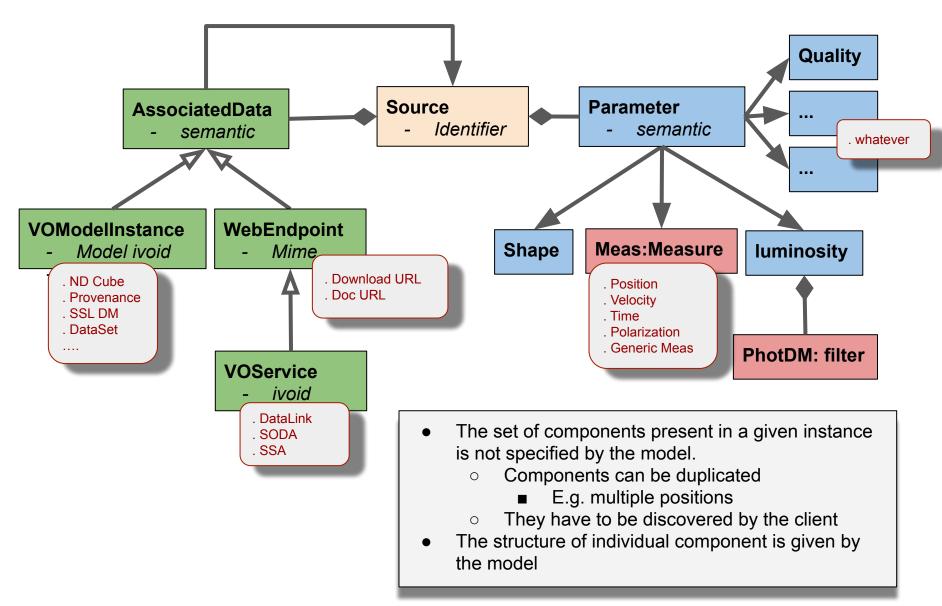


Model for Source Data

 All available data can be discovered and retrieved in the model instance

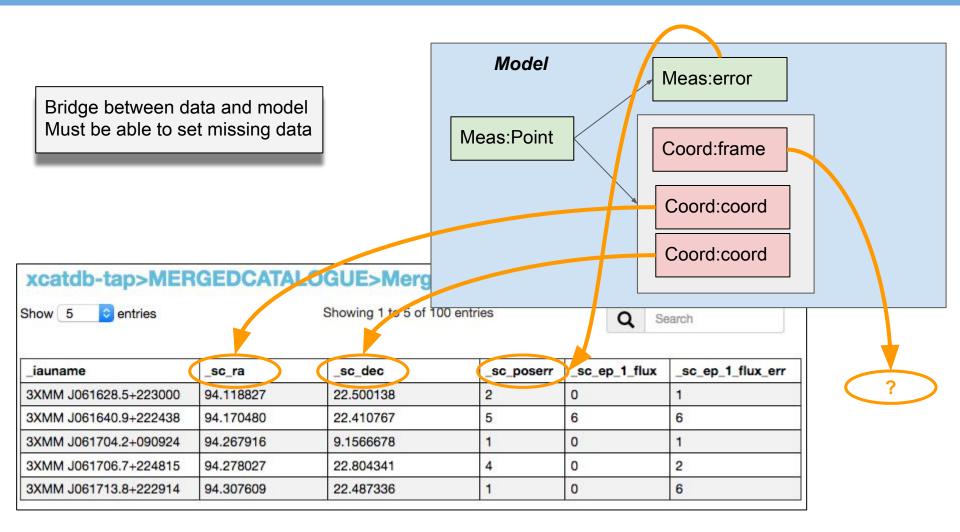


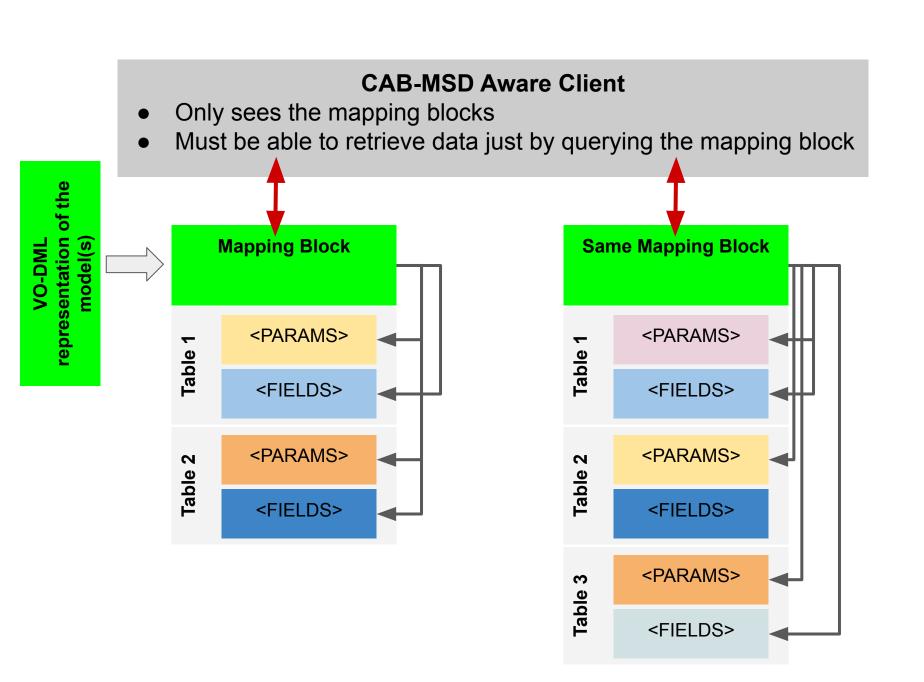
The Model: The UML Version





Data Annotation: Bridge connecting model with Data







Mapping Process Overhead

Not Critical: Mission database

- A few number of different products
- The source model mapping can be done once.

Critical: Archival Database (e.g. Vizier)

- Huge number of different products
 - Daily updated
- Mapping a source model comes in addition to usual work
 - Must be done each time a new dataset is published
- Must be a lightweight task
 - By minimising the amount of meta-data to be mapped
 - By using small reusable components

Very Critical: TAP services

- The possibility of automate the model mapping must be considered
 - This would be very useful for all VO stakeholders
- There is no concrete proposal yet but (some ideas anyway)
 - Avoid to use show stopper features: modularity



Data annotation: "Don't be evil" (Larry Page)

Shy Annotations

- #1: Able to be ignored
 - Do not break working things
 - The parser implementation shouldn't alter the existing code
 - The annotation implementation shouldn't alter the original data
- #2: To provide what is still missing in VOTables
 - A clear indication of the nature of the VOTable content.
- #3: Parser helper: Can be used at different levels
 - Just get the type of the VOTable content
 - Just the meta data
 - Just get column mapping
 - Get everything through the model



Data Annotation: Syntax

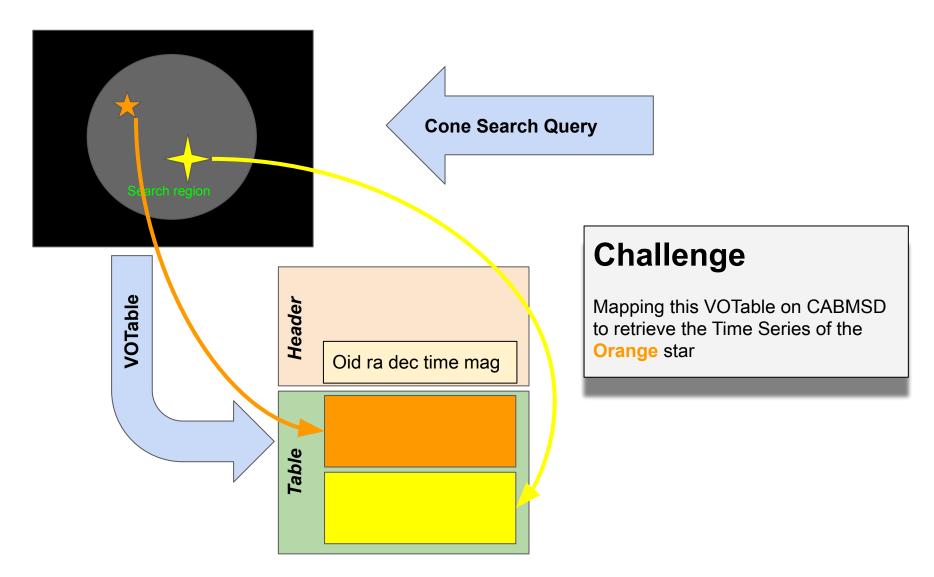
1. VO-DML mapping

- a. Mapping elements grouped outside of the data
- b. Model driven structure
- c. The mapping has its own schema
- d. Very chatty

My Proposal: Simplified syntax presented at College Park



ZTF example





ZTF Example: instanciated Components

https://irsa.ipac.caltech.edu/docs/program interface/ztf lightcurve api.html

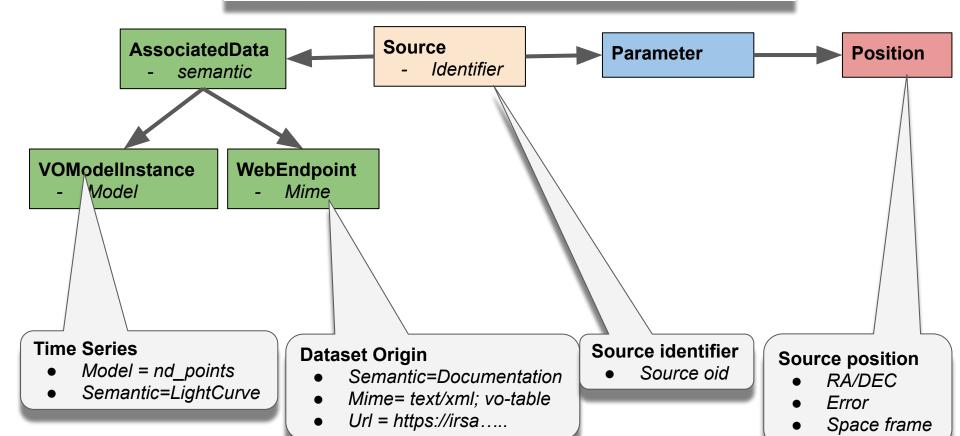
Behind the scenes

Typically there are multiple lightcurves for a given source position. Lightcurves are tagged in the ZTF lightcurve files by object identifier. As mentioned above, lightcurves corresponding to specific identifiers may be retrieved using the ZTF-LC-API via the ID parameter. Alternatively, this API also supports the retrieval of all lightcurves meeting positional and other constraints. When such constraints are supplied, a preliminary TAP query extracts the identifiers of all objects meeting those constraints from the ZTF objects table. Lightcurves corresponding to these identifiers are then retrieved from the ZTF lightcurve collection.

Sample queries

• Obtain the available g-band lightcurves within 5 arcsec of a source position:

https://irsa.ipac.caltech.edu/cgi-bin/ZTF/nph_light_curves?POS=CIRCLE 298.0025 29.87147 0.0014&BANDNAME=q



Source DM session - L. IVIII - CIOINIU

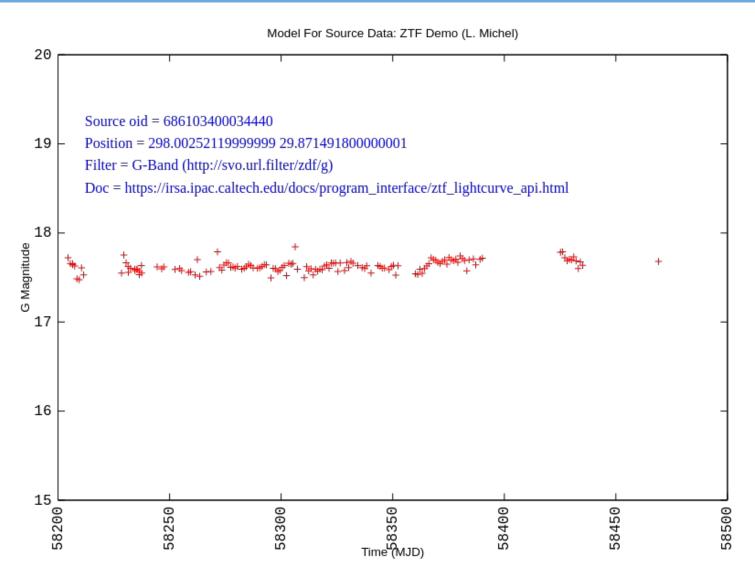


TS MappingPYTHON API Snippet

```
<INSTANCE dmrole="nd_point:point" dmtype="nd_point:Point">
   <FILTER key="oid" value="686103400034440" />
   <!--
    Time Stamp: MJD supported CAB-MSD s
    -->
   <INSTANCE dmrole="nd_point:TimeStamp" dmtype="coords:MJD">
        <INSTANCE dmrole="nd_point:TimeStamp.date" dmtype="ivoa:RealQuantity">
            <VALUE dmrole="ivoa:Quantity.unit" dmtype="ivoa:Unit" value="d"/>
           <!-- fields have no ID: let's take their names as identifiers -->
           <VALUE dmrole="ivoa:RealQuantity.value" dmtype="ivoa:real" ref="mjd" />
            <INSTANCE dmrole="coords:Coordinate.frame" ref="TimeFrame_TT_BARY"/>
       </TNSTANCE>
   </TNSTANCE>
   <!--
     Mag: The band is given by the filter
    -->
    <INSTANCE dmrole="nd_point:Mag" dmtype="nd_point:Mag">
        <INSTANCE dmrole="nd_point:Mag.coord" dmtype="nd_point:Coord">
            <VALUE dmrole="nd_point:mag.value" dmtype="ivoa:real" ref="mag" />
            <INSTANCE dmrole="nd_point:Mag.frame" ref="Filter_G"/>
       </INSTANCE>
       <COMPOSITION dmrole="meas:Measure.error" size="1">
            <INSTANCE dmrole="meas:Measure.error" ref="magerr"/>
       </COMPOSITION>
   </INSTANCE>
</INSTANCE>
```



ZTF Example: GNUPlot Output





Moving Ahead: Roadmap

- Assess the interest of the community for CAB-MSD
- Model
 - Distribute use case requirements over imported model components and CABMSD classes
- Data annotation
 - Define the schema of the mapping syntax
 - Assess mapping methods with data providers (including TAP)
- Client side
 - Define a language-agnostic API (à la Xpath?)
 - Develop a AstroPy module
 - Develop a Java client
- Start with a end to end implementation of selected cases
- Go in PR



Pointers

• Note:

https://github.com/lmichel/Model-For-Source-Data/

ZTF Demo

- https://github.com/lmichel/vodml-lite-mapping
- https://github.com/lmichel/vodml-lite-mapping/tree/master/src/test/java/t

Wiki Page

https://wiki.ivoa.net/twiki/bin/view/IVOA/SourceCatalogs





Do not read ahead....



Moving Ahead: One Big Open Question

- Which protocol could carry CAB-MSD instances?
 - The best (only) candidate is TAP
 - How annotate TAP responses now?
- Is it possible to do more than a simple demonstrator?
 - We could start with a few Vizier tables
 - And after?
 - Exercise with a specific TAP service?

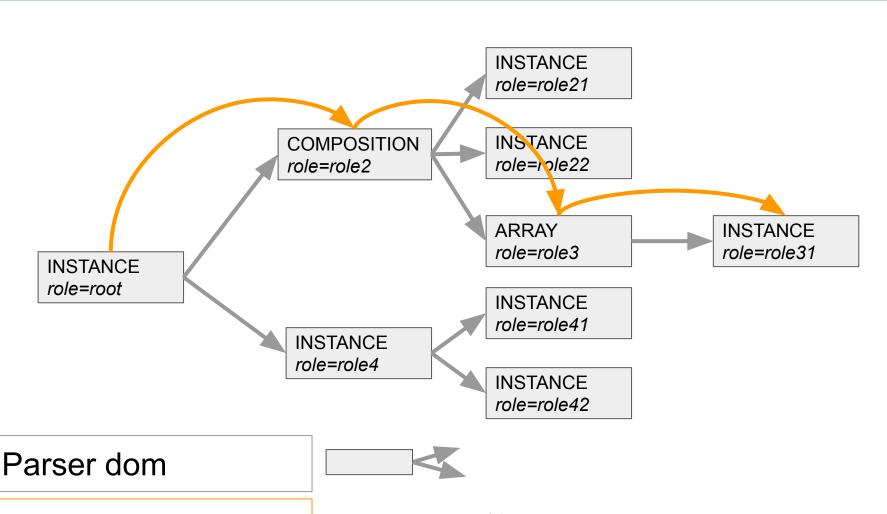


PYTHON API Snippet

```
* Extract the source measurements...
public void exploreDataSet() throws Exception{
    MappingElement dataSet = this.liteMappingParser.getFirstNodeWithRole("cab-msd:Source.identifier");
    this.cabmsdReport.sourceId = dataSet.getStringValue();
    dataSet = this.liteMappingParser.getFirstNodeWithRole("meas:EquatorialPosition.ra");
    this.cabmsdReport.ra = dataSet.getSubelementsByRole(IVOA REAL QUANTITY VALUE).get(0).getStringValue();
    dataSet = this.liteMappingParser.getFirstNodeWithRole("meas:EquatorialPosition.dec");
    this.cabmsdReport.dec = dataSet.getSubelementsByRole(IVOA REAL QUANTITY VALUE).get(0).getStringValue();
    this.cabmsdReport.docURL = this.liteMappingParser.getFirstNodeWithRole("cab-msd:WebUrl.url").getStringValue();
 * Extract the magnitude filter.
public void exploreFilters() throws Exception{
    MappingElement dataSet = this.liteMappingParser.getFirstNodeWithRole("cab-msd:FilterUrl");
    this.cabmsdReport.filterUrl = dataSet.getStringValue();
    dataSet = this.liteMappingParser.getFirstNodeWithRole("cab-msd:Filter.name");
    this.cabmsdReport.filterName = dataSet.getStringValue();
 * Extract the time series.
public void exploreData() throws Exception{
    MappingElement pointArray = this.liteMappingParser.getFirstNodeWithRole("nd point:points");
    this.cabmsdReport.nbPoints = pointArray.getLength();
    this.cabmsdReport.columnMapping = pointArray.getColumnRoles();
    for( int i=0 ; i<this.cabmsdReport.nbPoints ; i++ ){</pre>
       MappingElement row = pointArray.getContentElement(i);
        this.cabmsdReport.points.add(
                new Point(
                        row.getSubelementsByRole(IVOA REAL QUANTITY VALUE).get(0).getStringValue(),
                        row.getSubelementsByRole("nd point:mag.value").get(0).getStringValue()
       );
```



The Mapping DOM



What the client does

Node (role=role31) = Node (role=root)

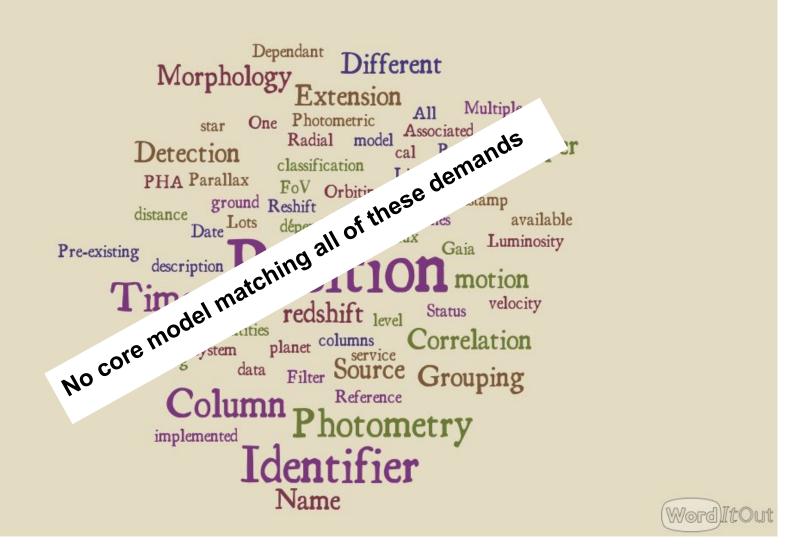
->Node (role=role2)

->Node (role=role3)

->Node (role=role31)



Paris Outcome





ZTF Example: Ass. data#2: T.S. origin

```
<INSTANCE dmrole="cab-msd:link" dmtype="cab-msd:VoInstance">
    <VALUE dmrole="cab-msd:link.semantic" value="LightCurve"/>
   <VALUE dmrole="cab-msd:VoInstance.model" value="nd point"/>
   <INSTANCE dmrole="cab-msd:VoInstance.Instance"/>
     ARRAY: One instance of cab-msd:VoInstance per DATATABLE row
    <ARRAY dmrole="nd point:TimeSeries.points">
         set of measurements defined by the LightCurve model (time-stamp + mag)
       <INSTANCE dmrole="nd point:TimeSeries.point" dmtype="nd point:Point">
           <FILTER key="oid" value="686103400034440" />
            Time Stamp: HJD not defined in STC, let's suppose that CAB-MSD supports it
           <INSTANCE dmrole="nd point:TimeStamp" dmtype="cab-msd:HJD">
                <INSTANCE dmrole="nd point:TimeStamp.date" dmtype="ivoa:RealQuantity">
                    <VALUE dmrole="ivoa:Quantity.unit" dmtype="ivoa:Unit" value="d"/>
                    <!-- fields have no ID: let's take their names as identifiers -->
                    <VALUE dmrole="ivoa:RealQuantity.value" dmtype="ivoa:real" ref="hjd" />
                <INSTANCE dmrole="meas:Time.coord" dmtype="coords:TimeStamp">
                    <INSTANCE dmrole="coords:Coordinate.frame" ref="TimeFrame TT"/>
                <COMPOSITION dmrole="meas:Measure.error" size="1">
                    <INSTANCE dmrole="meas:Measure.error" dmtype="meas:Error" >
                        <INSTANCE dmrole="meas:Error.ranError" dmtype="meas:Symmetrical">
                            <INSTANCE dmrole="meas:Symmetrical.radius" dmtype="ivoa:RealQuantity">
                                <VALUE dmrole="ivoa:Quantity.unit" dmtype="ivoa:Unit" value="sec"/>
                                <VALUE dmrole="ivoa:RealOuantity.value" dmtvpe="ivoa:real" value="1"/>
                            </INSTANCE>
                        </INSTANCE>
                    </INSTANCE>
                </COMPOSITION>
           </INSTANCE>
             Mag : the band is given by the filter
           <INSTANCE dmrole="root" dmtype="nd point:Mag">
                <INSTANCE dmrole="nd point:Mag.coord" dmtype="nd point:Mag">
                    <VALUE dmrole="nd point:mag.value" dmtype="ivoa:real" ref="mag" />
                    <INSTANCE dmrole="nd point:Mag.frame" ref="Filter G"/>
                </INSTANCE>
                <COMPOSITION dmrole="meas:Measure.error" size="1">
                    <INSTANCE dmrole="meas:Measure.error" ref="magerr"/>
               </COMPOSITION>
           </INSTANCE>
       </INSTANCE>
    </ARRAY>
</INSTANCE>
```



ZTF Example: Retrieving Data

```
* Parse the file and build the mapping maps
* athrows Exception
private void initParser() throws Exception {
   URL url = ZdfExplorer.class.getResource(VOTABLE RESOURCE);
   String sampleName =url.getFile();
   liteMappingParser = new LiteMappingParser(sampleName);
* Extract the source measurements
* @throws Exception
public void exploreDataSet() throws Exception{
   MappingElement dataSet = this.liteMappingParser.getFirstNodeWithRole("cab-msd:Source.identifier");
   this.zdfTimeSeriesReport.sourceId = dataSet.getStringValue();
   dataSet = this.liteMappingParser.getFirstNodeWithRole("meas:EquatorialPosition.ra");
   this.zdfTimeSeriesReport.ra = dataSet.getSubelementsByRole(REAL VALUE).get(0).getStringValue();
   dataSet = this.liteMappingParser.getFirstNodeWithRole("meas:EquatorialPosition.dec");
   this.zdfTimeSeriesReport.dec = dataSet.getSubelementsByRole(REAL VALUE).get(0).getStringValue();
* Extract the magnitude filter
* @throws Exception
public void exploreFilters() throws Exception{
   MappingElement dataSet = this.liteMappingParser.getFirstNodeWithRole("cab-msd:FilterUrl");
   this.zdfTimeSeriesReport.filterUrl = dataSet.getStringValue();
   dataSet = this.liteMappingParser.getFirstNodeWithRole("cab-msd:Filter.name"):
   this.zdfTimeSeriesReport.filterName = dataSet.getStringValue();
* Extract the time series
* @throws Exception
public void exploreData() throws Exception{
   MappingElement pointArray = this.liteMappingParser.getFirstNodeWithRole("nd point:TimeSeries.points");
    this.zdfTimeSeriesReport.nbPoints = pointArray.getLength();
    this.zdfTimeSeriesReport.columnMapping = pointArray.getColumnRoles();
   for( int i=0 ; i<this.zdfTimeSeriesReport.nbPoints ; i++ ){</pre>
       MappingElement row = pointArray.getContentElement(i);
       this.zdfTimeSeriesReport.points.add(
                new Point(
                        row.getSubelementsByRole(REAL VALUE).get(0).getStringValue(),
                        row.getSubelementsByRole("nd point:mag.value").get(0).getStringValue()
       );
```



The Model: The guideline

- What we do not need
 - o "This is a VO compliant source instance, make your business with it."
- What do we need
 - "Here is a set of data attached to this table row, help yourself"

The definition of what is a source is too much dependant from each use case to build a common model

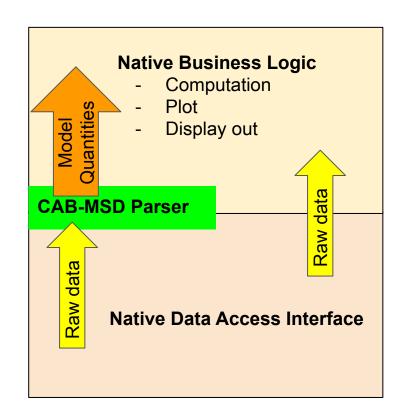


Inserting mapping parser in existing code

The parser code must be independent of any peculiar model

It must be able to retrieve individual quantities on demand

It must be designed in such a way it can be inserted in existing applications without breaking anything





Mapping Snippets Process

```
> mapping componants
                                 <INSTANCE dmrole="@@@@@@" dmtype="meas:EquatorialPosition">
                                   <COLLECTION size="-1">
  Fouatorial Position.xml
                                     <INSTANCE dmrole="meas:Measure.error" dmtype="meas:Error" ref="SymetricalError"/>
  GenericCoordFrame.xmt
                                   </COLLECTION>
                                   <INSTANCE dmrole="meas:EquatorialPosition.dec" dmtype="coords:Latitude">

▼ GenericMeasure.xml

                                     <INSTANCE dmrole="coords:Coordinate.frame" ref="SpaceFrame ICRS"/>
                                     <INSTANCE dmrole="coords:SpaceCoord.cval" dmtype="ivoa:RealQuantity">
  SpaceFrame ICRS.xml
                                       <VALUE dmrole="ivoa:Quantity.unit" dmtype="ivoa:Unit" ref="@@@@@"/>
  N SymetricalError.xml
                                       <VALUE dmrole="ivoa:RealQuantity.value" dmtype="ivoa:real" ref="@@@@@@"/>
  T me.xml
                                     </INSTANCE>
                                   </INSTANCE>
  7 FineFrame TT.xml
                                   <INSTANCE dmrole="meas:EquatorialPosition.ra" dmtype="coords:Longitude">
                                     <INSTANCE dmrole="coords:Coordinate.frame" ref="SpaceFrame ICRS"/>
  > zd annotated.xml
                                     <INSTANCE dmrole="coords:SpaceCoord.cval" dmtype="ivoa:RealQuantity">
 <INSTANCE discole="roca" dmtype="coords:TimeFrame" ID="TimeFrame TT">
    <INSTANCE omrole="coords:TimeFrame.refPosition" dmtype="coords:StdRefLocation">
      <VALUE value="HELIOCENTRIC" dmrole="coords:StdRefLocation.position" dmtype="ivoa:string" ref="@@@@@@"/>
    </INSTANCE>
    <VALUE value="TT" dmrole="coords:TimeFrame.timescale" dmtype="ivoa:string" ref="@@@@@"/>
</INSTANCE>
                                <INSTANCE dmrole="root" dmtype="meas:Time">
                                  <INSTANCE abstr="true" dmrole="meas:Time.coord" dmtype="coords:TimeStamp">
                                   <INSTANCE dmrole="coords:Coordinate.frame" ref="TimeFrame TT"/>
                                  <COLLECTION size="-1">
                                   <INSTANCE dmrole="meas:Measure.error" ref="SymetricalError"/>
                                  </COLLECTION>
                                </INSTANCE>
<INSTANCE dmrole="root" dmtype="coords:SpaceFrame" ID="SpaceFrame ICRS">
    <VALUE value="J2000" dmrole="coords:SpaceFrame.equinox" dmtype="coords:Epoch" ref="@@@@@@"/>
    <VALUE dmrole="coords:SpaceFrame.planetaryEphem" dmtype="ivoa:string" ref="@@@@@@"/>
   <VALUE value="ICRS" dmrole="coords:SpaceFrame.spaceRefFrame" dmtype="ivoa:string" ref="@@@@@@"/>
   <INSTANCE dmrole="coords:SpaceFrame.refPosition" dmtype="coords:StdRefLocation">
      <VALUE value="GEOCENTER" dmrole="coords:StdRefLocation.position" dmtype="ivoa:string" ref="@@@@@@"/>
    </INSTANCE>
</INSTANCE>
```



The model: Appropriate decription level

1. Just saying what data are

a. This is a symmetrical error

2. Saying how to use these data

a. This is a symmetrical error defined at 3sigma

3. Giving information about the data provenance

This symmetrical error defined at 3sigma is function of (position, pm, RV mag)



Motivation for a Source Model

J/A+A/532/A103/IC4665 Photometry and proper motions in IC4665 (Lodieu+, 2011)

2011A&A

Post annotation

Coordinates, photometry, proper motions, and physical parameters for IC4665 stars (tables A1, B1 and C1 of paper) (1533 rows)







0	start AladinI	Lite //	ple	ot the output	<u>क</u> वा	uery usi	ng TAP	/SQL									
Full	_RAJ2000	_DEJ2000	Mm	Name	Zmag	Ymag	Jmag	Hmag	Kmag	pmRA	pmDE	logL	Mass	GCS	Simbad	RAJ2000	DEJ2000
G 37	"h:m:s"	"d:m:s"			mag	mag	mag	mag	mag	mas/yr	mas/yr	[Lsun]	Msun			"h:m:s"	"d:m:s"
△▼	17 42 05 0200	AT 000	△▼	174205 02 052412 0	15 112	14.525	12.040	12.200	12.021	1.00	10.56	1.20	0.440		Circle J	17 42 05 02	.05.24.12.0
_		+05 24 13.900		174205.93+052413.9													+05 24 13.9
		+05 14 17.900		174206.02+051417.9		The second second											+05 14 17.9
3	17 42 09.5800	+05 21 12.600	C	174209.58+052112.6	15.693	15.200	14.587	13.944	13.615	-36.93							+05 21 12.6
4	17 42 16.9500	+05 26 51.300	C	174216.95+052651.3													+05 26 51.3
5		+05 56 26 200		174217.78+055626.2	16.616	16.024	15 344	14.767	14.377	-25.95	-12.29	-1.93	0.160	GCS	Simbad	17 42 17.78	+05 56 26.2
6	SOURCE : 174325.35+052128.5													GCS	Simbad	17 42 18.00	+05 49 25.5
7	POSITION: 17 43 25.35 +05 21 28.5													GCS	Simbad	17 42 18.19	+05 53 53.3
8	P.MOTION: -50.22 -46.39													GCS	Simbad	17 42 20.29	+05 55 56.5
9	MAGS : I=18.264 z=17.664 Z=17.763 Y=17.058 J=16.386 H=15.803 K=15.392													GCS	Simbad	17 42 20.79	+05 46 35.6
10	SOURCE : 174330.63+050217.5														Simbad	17 42 21.08	+05 43 13.9
7.7	110														Simbad	17 42 23.55	+05 38 23.5
12	POSITION: 17 43 30.63 +03 02 17.3														+05 06 06.1		
13	P.MOTION: -19.53 -10.09													GCS	Simbad	17 42 25.41	+06 21 05.3
14	MAGS :	I=18.312 z=	=17.	641 Z=17.760 Y=	17.14	4 J=1	6.457	H = 15	.895	K=15.5	63						+05 29 47.2
1.5	SOURCE :	174331.38+0	0527	23.3													+06 22 19.8
16	POSITION:	17 43 31.38	3 +0	5 27 23.3													+06 20 14.6
17	P.MOTION:	-1.24 7.69		The section of the se													+05 26 40.7
7.6			=16.	854 Z=16.912 Y=	16.39	5]=1	5.779	H=15	.218	K=14.8	65)	0.078	GCS	Simbad	17 42 28.93	+05 54 53.8

: I=17.350 z=16.854 Z=16.912 Y=16.395 J=15.779 H=15.218 K=14.865 MAGS

SOURCE: 174331.39+053403.6

POSITION: 17 43 31.39 +05 34 03.6

P.MOTION: -904.33 -1413.85

MAGS : I=18.705 z=18.013 Z=18.107 Y=17.431 J=16.745 H=16.184 K=15.753

SOURCE: 174331.77+063945.3

POSITION: 17 43 31.77 +06 39 45.3

P.MOTION: -2.70 -9.07

: I=16.149 z=15.739 Z=15.778 Y=15.317 J=14.662 H=13.971 K=13.697 MAGS

0.336 GCS Simbad 17 42 28.94 +06 20 28.0

0.524 GCS Simbad 17 42 31.91 +06 18 49.5