

VAO SIAv2 Prototype

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Motivation

- Heidelberg

- Call for creation of prototypes various approaches to cube data access
- Data Providers: First show discovery and downloading of whole datasets
- VAO response
 - Discovery and static download first priority
 - Sub-cube access (e.g. cutouts): as time allows

- VAO Project Goals

- Demonstrate to the IVOA what an SIAv2 service would look like
 - Ability to see under the hood as well.
- Exercise key science use cases to assess the standards
 - Provide feedback that can constructively inform further development of the standards
 - Focused selection of data based on coverage



The VAO approach to SIAv2

- See IVOA Twiki page: SIA2VAOPrototype
<http://wiki.ivoa.net/twiki/bin/view/IVOA/SIA2VAOPrototype>
- Development “phases”
 - Initial Planning and setting scope (white paper)
 - **Priority: discovery and static download**
 - Updating the relevant documents: ImageDM and SIAv2
 - Implementation based on DALServer toolkit
 - Testing and evaluation of deployed prototype



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- Development “phases”
 - Initial Planning and setting scope (white paper)
 - Updating the relevant documents: ImageDM and SIAv2
 - “Froze” documents to *baseline* version:
 - Key for testing/evaluation: what are we testing against?
 - Used a change control process to allow only critical changes
 - IVOA versions continue to evolve; thus, baseline is a minor fork.
 - SIAv2: VAO-SIA-2.0-20130830.pdf
 - Implementation based on DALServer toolkit
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 - Updating the relevant documents: ImageDM and SIAv2
 - Implementation based on DALServer toolkit
 - DALServer: a Java-based toolkit developed by NVO/VAO
 - Collected wide variety of 2-D and N-D images
 - ALMA, VLA, JVLA, Heracles, OSIRIS (Keck), Califa, JCMT, JWST, CARMA
 - Traditional 2D images, 3D radio cubes, moment maps, sparse images, integral optical spectrograph
 - Extracted/transformed FITS metadata, loaded into a database
 - Noted where we needed to “make things up” (mainly identifiers)
 - Deployed to server at NRAO
 - Testing and evaluation of deployed prototype



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- Development “phases”
 - Initial Planning and setting scope (white paper)
 - Updating the relevant documents: ImageDM and SIAv2
 - Implementation based on DALServer toolkit
 - Testing and evaluation of deployed prototype
 - Developed a set of Test Queries based on spec documents
 - Independent of implementation
 - Science-driven, focused on coverage: spatial, spectral, temporal, & polarization
 - Assembled Test Plan that included tests of compliance against our baseline documents
 - Tested for building and deployment on Linux/Apache/MySQL/Tomcat platforms



VAO Implementation

- Based on VAO baselines of ImageDM and SIAv2 documents
- Further limits on scope:
 - Synchronous version of service (**/sync**)
 - Focus is on **REQUEST=queryData**
 - Assume **INTERSECT=OVERLAPS** (default)
 - Assume **MODE=archival**; i.e. return static images
- Supported Input parameters
 - Required parameters: **POS, SIZE, BAND, TIME, POL, FORMAT**
 - Some additional optional parameters support, but not tested
- Output columns:
 - Required and recommended columns supported
 - Note use of VOTable **GROUPS** to associate related columns



Results

- Deployed prototype service with base URL:
<http://vaosa-vm1.aoc.nrao.edu/ivoa-dal/siapv2/>
- Report on IVOA TWiki page: SIA2VAOPrototype
<http://wiki.ivoa.net/twiki/bin/view/IVOA/SIA2VAOPrototype>
 - Includes clickable test queries
- Source code available:
 - Browse on-line:
<http://dev.usvao.org/vao/browser/vao/prototype/dalserver/branches/siav2aproto>
 - Download:
<http://dev.usvao.org/siav2/dalserver-siav2proto.1.tar.gz>
 - “Friendly IVOAers” can build and deploy on own platform
 - Requires Apache, Java, Tomcat, MySQL, Python
 - See prototype/README



Feedback to standards development

- General Assessments:
 - Successful demonstration of a service in the mode of SSA
 - Simple queries are compact, readable, and easily editable directly
 - Much improved metadata returned over SIAv1:
 - Can readily see what axes are found and in what order
 - Description of coverage is independent of the axes
 - E.g. Can see spectral coverage even if image does not formally have a spectral access
 - Does not depend on axis order, direction
 - Can determine what pixels measure (unit and UCD)
 - Can determine if dataset contains multiple image HDUs (Dataset.Image.Nsubarrays)
 - Browsing HDU metadata via Dataset.Image.Dataref not demonstrated
 - Flexible to complex, leading-edge N-D datasets
 - Proof of concept: study: applicable to x-ray event list



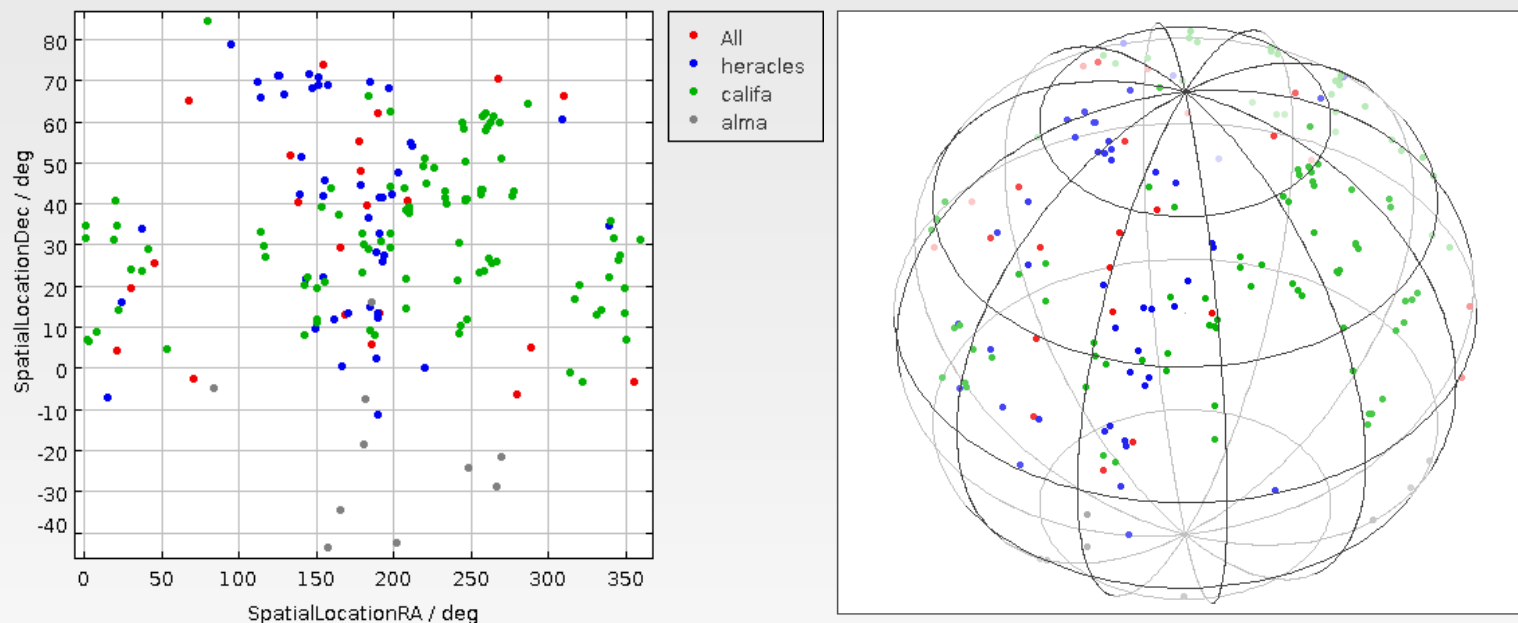
Feedback to standards development

- Various minor issues
 - Alternate Spectral coverage information (freq., energy, velocity) is useful to know
 - Make returning of Char.SpatialAxis.Coverage.Support.Area as “recommended”
 - STC-S description of spatial coverage
 - ImageDM needs clarification of UType definition
 - Metadata do not adequately identify compressed images
 - Consider search constraint on spectral line species
 - Make returning of Char.FluxAxis.Unit as “recommended”
 - Consider search constraint that tests pixel content
 - Against Char.FluxAxis.UCD? Char.FluxAxis.Unit?
 - Is SUBTYPE relevant?
 - Important for theory data: find theoretical optical depth images



Feedback to standards development

Distribution of test data collection



Returning spatial positions

- Current spec calls for positions to be an RA-Dec pair of numbers in single column
 - Image spatial center, lower & upper limits
- Cannot be interpreted by common tools
 - Requires tool understand DM to “know” pair is a position
- Better to render RA/Dec in separate columns
 - Need UTypes defined to identify components of position
 - Use GROUPs to associate RA and Dec components



Feedback to standards development

Handling unknown data in queries (NULLs)

- Consider query requesting data for time domain analysis:
`/sync?REQUEST=querydata&TIME=1992-01-01/1997-01-01`
 - Current spec: if metadata for constraint is not known, the image should be returned in results
 - Thus, result contains (many) images that may not actually be within time range
 - Prototype: 4 images known to be in range, 290 returned
 - Rationale: don't let client miss potentially useful images
 - let client further filter on the client side
 - However, if time coverage is not known, client will be not be able to determine applicability post-query either
- Possible Solution
 - Extra parameter that provides a switch controlling whether to return images where information is unknown
 - Consider carefully what default behavior should be



SIAv2 in context of Cube Access

- What distinguishes SIAv2 from SIAv1
 - Full coverage querying; not just by position
 - Richer optional parameters that help refine queries:
 - Identifiers: Isolating specific images, collections, of source derivation
 - Processing levels, targets, sensitivity
 - Metadata model that is better suited to browsing N-d cubes
 - Sub-cube access (cutouts, subsetting, reprojections, ...)
 - Client-directed “cutouts” separated explicitly from the discovery
 - Client uses the data returned in the discovery response to craft inputs into `AccessData` query
 - Allows for requesting richer transformations
 - Staging data on the server
 - Not currently specified



SIAv2 in context of Cube Access

- Potential for take-up

- By clients

- Parameter approach demonstrated to be convenient for human and agent clients alike
 - See PyVO Focus Demo
 - Small set of core discovery parameters
 - Common queries are compact, readable, editable

- By data providers

- SIAv1 has demonstrated large take-up
 - Small set of core metadata:
 - 6 required, others “strongly recommended” depending on the coverage of the data.
 - Aided if our approach is to adapt onto the metadata already maintained by data provider
 - As opposed to in effect requiring separately maintained database tables.



Summary

- We've demonstrated what an SIAv2 service would look like
 - Transparent process and software
 - Please poke
- Assessed service...
 - ...against a list of science driven test queries
 - ...against baseline versions of specs
- We've learned some useful lessons
 - A number of useful features, improvements over SIAv1
 - Collected useful feedback to standards development process
 - Highlighted issues:
 - Encoding spatial positions
 - How we deal with unknown metadata
- Demo informs how SIAv2 can enable cube access